TEMPERATURE FIELDS IN STRUCTURAL ELEMENTS

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We examine the application of the variational Kantorovich process for an approximate solution of the two-dimensional nonlinear heat-conduction problem. We provide a comparison with a computer-derived solution.

Let the functional (Mev) be defined in some region v with the boundary S (Fig. 1):

$$I[T(M)] = \int_{v} \left[(\lambda \nabla T)^{2} - 2q_{v} \int_{0}^{T} \lambda dT \right] dv + 2 \int_{S} \sum_{m=1}^{k} \gamma_{m} f_{m} dS.$$
 (1)

Let us equate the variation of functional (1) to zero:

$$\delta I = 2 \int_{v} \left[\lambda \frac{\partial \lambda}{\partial T} (\nabla T)^{2} \delta T + \lambda^{2} \nabla T \nabla (\delta T) - q_{v} \lambda \delta T \right] dv + 2 \int_{S} \sum_{m} \frac{\partial f_{m}}{\partial T} \gamma_{m} \delta T dS = 0.$$
 (2)

By transformation and with the Ostrogradskii formula we obtain

$$\int_{r} \left[\nabla \left(\lambda \nabla T \right) + q_{v} \right] \delta T \lambda dT - \int_{S} \left[\lambda \nabla T + \sum_{m} \frac{Y_{m}}{\lambda} \frac{\partial f_{m}}{\partial T} \right] \delta T \lambda dS = 0.$$
 (3)

Since $\lambda > 0$, we come to the steady-state thermal problem with boundary conditions of the general type:

$$\nabla (\lambda \nabla T) + q_v = 0, \tag{4}$$

$$\left[\lambda \frac{\partial T}{\partial n} + \sum_{m} \frac{\gamma_{m}}{\lambda} \frac{\partial f_{m}}{\partial T}\right]_{S} = 0.$$
 (5)

Having selected the coordinate system for the function $u_i(M)$, we will seek its approximate solution among the class of functions satisfying the boundary conditions (5) in the form

$$T_n = \sum_{i=1}^n s_i u_i + u_s, \tag{6}$$

and here $s_i(x_k)$ is determined from the condition of minimizing the original functional (1).

To construct the coordinate system we use the function $u_0(N)$, which is a solution of the problem (L $\subset S$, $D \subset v$):

$$\nabla (\lambda \nabla u_0) + q_n(N) = 0, \tag{7}$$

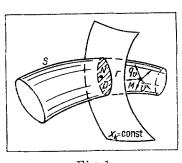
$$\left[\lambda \nabla u_0 + \sum_m \frac{\gamma_m}{\lambda} \frac{\partial f_m}{\partial T}\right]_{\Gamma} = 0, \tag{8}$$

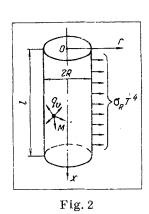
in which λ and f_m are regarded as the function $u_0(N)$.

For the sake of determinacy, let us examine the following problem of finding the temperature field in a cylindrical heat-evolving element with arbitrarily positioned sources within the volume (Fig. 2):

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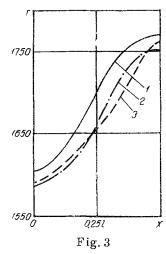


Fig. 1

Fig. 1. Region for which the original functional is determined.

Fig. 2. Theoretical diagram for the cooling of a fuel element in the case of cylindrical symmetry.

Fig. 3. Found axial temperature distribution in fuel elements (T, °K): 1) first approximation; 2) second approximation; 3) electronic digital computer.

$$\nabla \left[\lambda_0 \left(1 + \beta T\right) \nabla T\right] + q_0 w_x(x) \, w_r(r) = 0,\tag{9}$$

$$[T'_x]_{x=0, x=l} = 0, \ [\lambda_0 (1+\beta T) T'_r + \sigma_R T^4]_{r=R} = 0.$$
 (10)

It is not difficult to see that the thermal problem (9)-(10) is equivalent to the variational problem for functional (1) when

$$\left[\gamma_{i}\right]_{r=R} = \sigma_{R}, \quad \left[f_{i}\right]_{r=R} = \lambda_{0} \int_{R}^{T} T^{4} \left(1 + \beta T\right) dT.$$

We turn to the dimensionless variables

$$\rho = \frac{r}{R}, \quad \psi = \frac{x}{R}, \quad t = 1 + 2\beta \int_{0}^{T} (1 + \beta T) dT$$
 (11)

and the notations

$$\sigma = \frac{2\sigma_R R}{\lambda_0 \beta^3}, \quad q = \frac{2q_0 R^2 \beta}{\lambda_0}. \tag{12}$$

The original problem is then written in the form

$$\Delta t + q w_0 w_0 = 0, \tag{13}$$

$$[t'_{\psi}]_{\psi=0, \psi=L/R} = 0, \quad [t'_{\rho} + \sigma(; \overline{t} - 1)^{4}]_{\rho=1} = 0.$$
 (14)

According to (6), we seek the approximate solution in the form

$$t_n = u_0(\rho) \left[s_0(\psi) + \sum_{i=1}^n \alpha_i s_i(\psi) \right], \tag{15}$$

where $\alpha_{2i-1} = \rho^{2i-1}$ and $\alpha_{2i} = (1-\rho)^{2i}$.

In accordance with our original idea, the function $u_0(\rho)$ is defined as the solution of the problem

$$(\rho u_0)' + \rho w_\rho = 0, \tag{16}$$

$$[u_0' + \sigma (\overline{u_0} - 1)^4]_{\rho} = 1, \tag{17}$$

which has the form

$$u_0 = -\Phi(\rho) + C, \quad \Phi(\rho) = \int \frac{1}{\rho} \int w_\rho \rho d\rho, \tag{18}$$

where C is a constant determined from (17).

Having determined the total heat release q_{tot} in a cylinder of unit length for fixed ψ and an averaged heat-transfer coefficient Ω (from the heat-balance condition), we find $s_0(\psi)$ as the solution for the problem of a fuel element, i.e.,

$$s_0'' - 2\Omega s_0 + q_{\Pi} w_{\Psi} = 0, \ s_0'(0) = s_0'(l/R) = 0.$$
 (19)

Since the approximate solution is sought among the class of functions satisfying the boundary conditions, the original functional (1) in the notation of (11) and (12) assumes the form

$$I = \int_{\psi=0}^{1/R} \int_{\rho=0}^{1} \left[(t'_{\rho})^2 + (t'_{\psi})^2 - 2qtw_{\psi}w_{\rho} \right] \rho d\rho d\psi. \tag{20}$$

We will substitute the expression for t_n from (15) into the appropriate minimization of functional (20), we will integrate with respect to ρ , and we will introduce the dimensionless coefficient of the Euler system of equations

$$a_{ij} = \int_{0}^{1} u_{0}^{2} \alpha_{i} \alpha_{j} \rho d\rho, \quad c_{i} = \int_{0}^{1} w_{\rho} \alpha_{i} \rho d\rho, \quad f_{i} = \int_{0}^{1} u_{0}^{2} \alpha_{i} \rho d\rho,$$

$$b_{ij} = \int_{0}^{1} \left(u_{0}^{\prime 2} \alpha_{i} \alpha_{j} + 2 u_{0}^{\prime} u_{0} \alpha_{i} \alpha_{j} + u_{0}^{2} \alpha_{i} \alpha_{j} \right) \rho d\rho,$$

$$d_{i} = \int_{0}^{1} \left(u_{0}^{\prime 2} \alpha_{i} + u_{0}^{\prime} u_{0} \alpha_{i}^{\prime} \right) \rho d\rho, \quad h_{i} = \int_{0}^{1} \sigma \left(u_{0}^{\prime} \alpha_{i} + u_{0} \alpha_{i}^{\prime} \right) \rho^{2} d\rho.$$

$$(21)$$

After integration we turn to the one-dimensional functional which must achieve a minimum for the family of functions determined from the system

$$\sum_{i} (a_{hi}s_{i}^{r} - b_{hi}s_{i}) = \varphi_{h}; \quad i, \ k = 1, 2, \ldots, n - 1,$$
(22)

where $\varphi_k = d_k s_0 + h_k - q c_k w_\psi - f_k s_0^{\prime\prime}$ is a known function.

With this selection of s_0 we can assume that

$$(s_{2i-1}/s_0)^m \ll 1 \ (m=2, 3, \ldots).$$
 (23)

Then, substituting (15) into (14), with consideration of (23) we obtain the closing condition which is linear with respect to s_{2i-1} .

As an example we determined the temperature distribution in a fuel element. This was compared with the solution obtained on a digital computer. The results shown in Fig. 3 show that the accuracy is sufficient for engineering calculations (3-4%).

NOTATION

T is the temperature;

R, l are the radius and the length of the cylinder;

x, r are the axial and radial coordinates;

λ is the coefficient of thermal conductivity;

q is the specific heat release;

f, γ are functions characterizing the form of the boundary conditions;

w is a function characterizing the distribution of the internal sources;

u is a coordinate function;

s is the minimizing function;

t is the dimensionless function of temperature;

 ψ, ρ are dimensionless axial and radial coordinates;

σ is the reduced radiation factor.

Symbols

- 0 denotes initial;
- x, ψ denote axial;
- \mathbf{r}, ρ denote radial;
- v denotes volume.

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